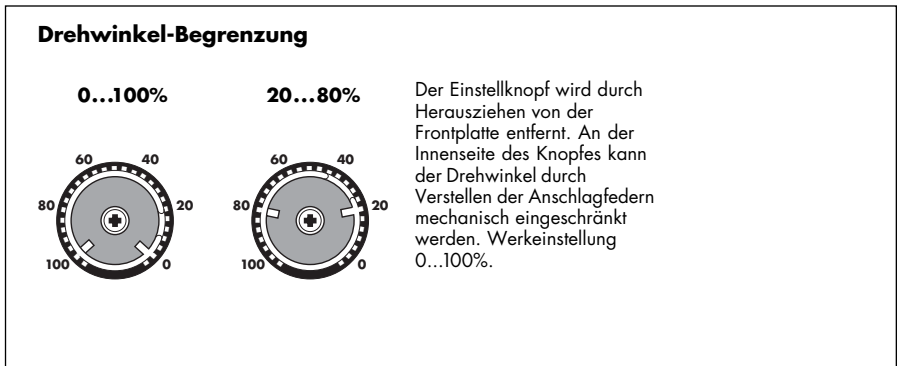
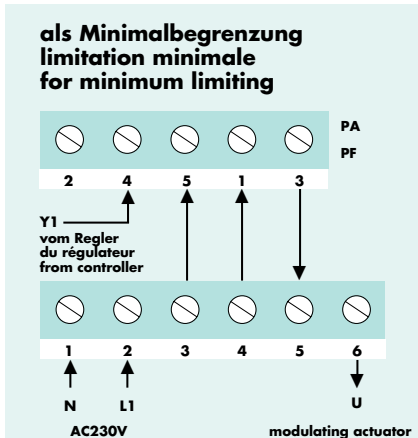
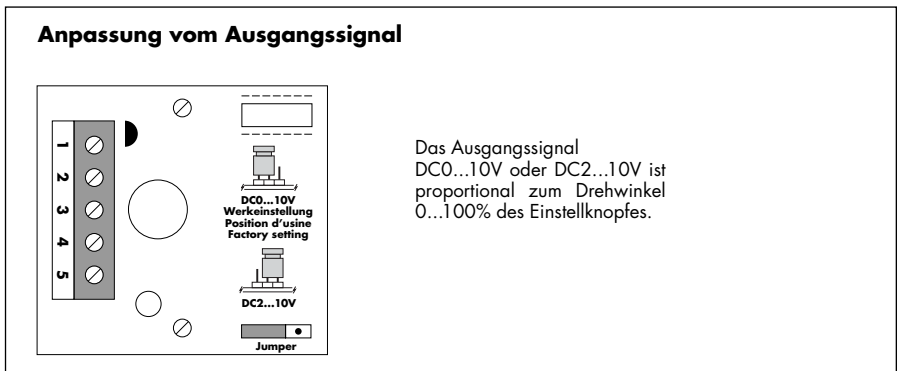
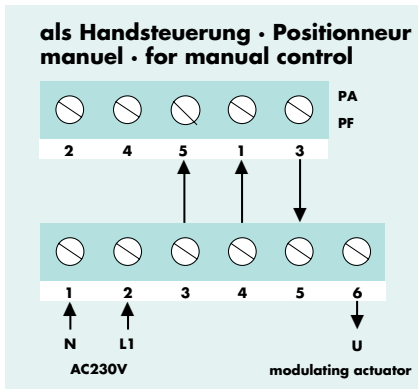


**Technische Daten**

|                  |                |                             |
|------------------|----------------|-----------------------------|
| PA               | Stellungsgeber | 0...100% für Aufputzmontage |
| PF               | Stellungsgeber | 0...100% für Frontaufbau    |
| Zu Stellantriebe | Typ            | DM...2.2(S) / MM2.2(S)      |
| Betriebsspannung |                | DC15V+                      |
| ab               |                | DM...2.2(S) / MM2.2(S)      |
| Frequenz         | Hz             | -                           |
| Ausgangssignal   | U              | DC0(2)...10V                |
| Ausgangsleistung |                | für max. 5 Stellantriebe    |
| Reglersignal     | Y1             | DC0(2)...10V                |



## ACCESSORY

Stellungsgeber PA - PF für stetige Antriebe AC/DC24V

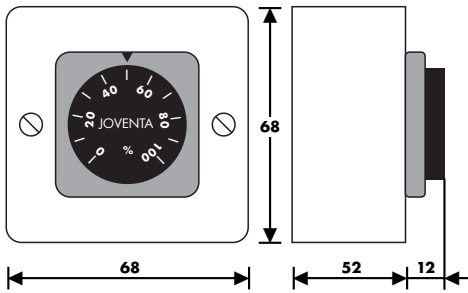
6.20

Positionneur PA - PF pour servomoteurs proportionnels AC/DC24V

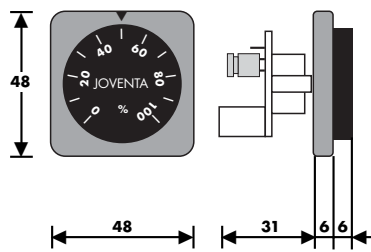
Transmitters PA - PF for actuators modulating AC/DC24V

### Abmessungen (mm) • Dimensions (mm) • Dimensions (mm)

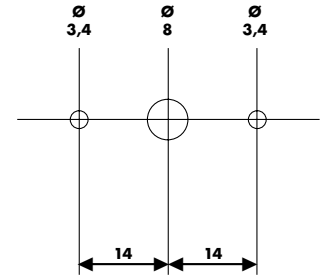
PA mit Aufputzgehäuse  
PA pour montage apparent  
PA in surface-mounting box



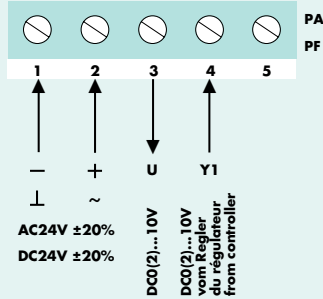
PF für Frontaufbau  
PF pour montage frontal  
PF for front mounting



Bohrplan  
Plan de montage  
Drilling template



### Anschluss-Schema • Schema de raccordement • Wiring diagram

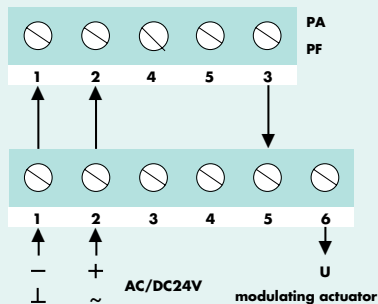


### Nomenclature/Specification/Technical data

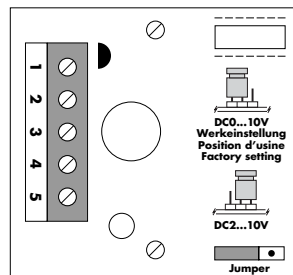
|    |                      |                                |
|----|----------------------|--------------------------------|
| PA | Stellungsgeber       | 0...100% für Aufputzmontage    |
| PF | Stellungsgeber       | 0...100% für Frontaufbau       |
| PA | Positionneur         | 0...100% pour montage apparent |
| PF | Positionneur         | 0...100% pour montage frontal  |
| PA | Position transmitter | 0...100% for surface mounting  |
| PF | Position transmitter | 0...100% for front mounting    |

|  |     |   |
|--|-----|---|
| Zu Stellantriebe · Pour servomoteur · For actuators    | Typ | DMN1.2 / DM...1.1(S)<br>DM1.1F(S) / SM1... (S)<br>MM1.1(S)                    |
| Betriebsspannung · Tension de service · Power supply   |     | AC/DC24V ±20%   |
| Frequenz · Fréquence · Frequency                       |     | 50-60 Hz  |
| Ausgangssignal · Signal de sortie · Output signal      | U   | DC0(2)...10V  |
| Ausgangsleistung · Puissance de sortie · Output rating |     | für max. 5 Stellantriebe<br>pour max. 5 servomoteurs<br>for up to 5 actuators |
| Reglersignal · Signal du régulateur · Control signal   | Y1  | DC0(2)...10V  |

### als Handsteuerung • Positionneur manuel • for manual control



### Anpassung vom Ausgangssignal Adaption du signal de sortie • Output signal matching

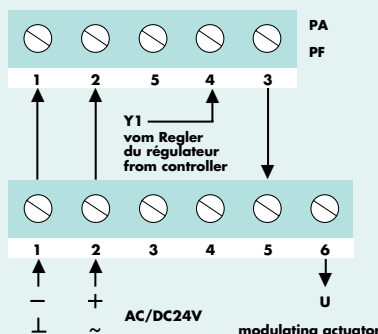


Das Ausgangssignal DC0...10V oder DC2...10V ist proportional zum Drehwinkel 0...100% des Einstellknopfes.

Le signal de sortie DC0...10V ou DC2...10V est proportionnel à l'angle de rotation 0...100% du positionneur.

The output signal DC0...10V or DC2...10V is proportional to 0...100% rotation of the adjuster knob.

### als Minimalbegrenzung limitation minimale for minimum limiting



### Drehwinkel-Begrenzung Limitation de l'angle de rotation • Limitation of rotation angle

